Paper / Subject Code: 31002 / MECHANICAL MEASUREMENT AND CONTROL

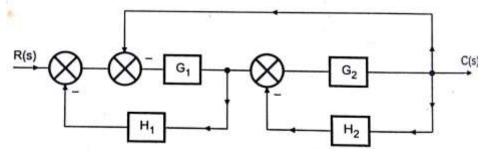
1T01415 - T.E.(MECHANICAL)(Sem V) (CBSGS) / 31002 - MECHANICAL MEASUREMENT AND CONTROL
O. P. Code: 21835

(3 Hours) [Total marks: 80]

Instructions:

- 1. Question 1 compulsory.
- 2. Attempt any **three** questions from the remaining **five** questions.
- 3. Assume suitable data, **if necessary**.
- 4. Figures/sketches carry weightage.
- Q1) a) Take a suitable example of a Pressure gauge and draw its generalized measuring flow chart 10 explaining every element with function.
 - b) What are Encoders? With a neat sketch explain the working of an Incremental and Absolute optical encoder. Give examples of their use.
- Q2) a) Define Resolution, Precision and Accuracy of a measuring instrument. 7

 A moving coil voltmeter has a uniform scale with 100 divisions, the full scale reading is 200v and 1/10th of a scale division can be estimated with a fair degree of certainty. Determine the resolution of the instrument in volt.
 - b) What is a Stroboscope? A stroboscope projects 6000 flashes per minute on a disc with 10 patterns mounted on the shaft of a machine. Find the speed of machine if the disc appears stationary and has a single point image. What will be the two possible shaft speeds if 10 points appear to be revolving once in 15 second? Draw your solution.
 - c) Illustrate the working principle of "L.V.D.T." for displacement measurement.
- Q3) a) What are Bi-metallic Thermometers? State the principle of operation and explain with neat 8 diagram the deflection measured in industrial type bi-metallic thermometers.
 - b) A system is given by differential equation, $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 8y = 8x$, 12 where y = output and x = input. Determine all time domain specifications for unit step input and plot the response curve.
- Q4) a) Obtain the Transfer function for the Block diagram using Standard Block reduction rules. 10



b) Enumerate the types of pressure measurement devices w.r.t. to pressure levels to be measured. State the working principle of any one transducer for each pressure level.

TURN OVER

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Q5)	a)	 A second order system has unit feedback and open loop T.F. G (s) = 500 / s (s+15). a) Draw the block diagram for closed loop system and write the characteristic equation. b) Calculate the Damping ratio and natural frequency, peak time, peak overshoot and setting time for the system output when excited by step input. c) Sketch the transient response for unit setup input d) If the input is ramp of 0.5rad/sec, calculate steady state error. 	10
	b)	Sketch the Root Locus for the given system having G (s). H (s) = $K(s + 0.5)$ /s ($s^2 + 2s + 2$). Comment on its stability.	10
Q6)	a)	What do you understand by a State-space modeling of a system? What is its significance for theory and practical applications? Comment.	5
	b)	Write a short note on PID controller.	5
	c)	A feedback system has $G(s) H(s) = 100 (s+4) / s (s+0.5) (s+10)$. Draw Bode plot and comment on its stability.	10