Program: BE Electrical Engineering

Curriculum Scheme: Revised 2016

Examination: Final Year Semester VII

Course Code: EEC702 and Course Name: Drives and Control

Time: 1 hour Max. Marks: 50

Note to the students:- All the Questions are compulsory and carry equal marks .

Q1.	Fans have load torque proportional to	
Option A:	Inverse of square of speed	
Option B:	Square of speed	
Option C:	Inverse of speed	
Option D:	Speed	
Q2.	Equilibrium point is when	
Option A:	Load torque ≠ Motor torque	
Option B:	Load torque < Motor torque	
Option C:	Load torque = Motor torque	
Option D:	Load torque > Motor torque	
Q3.	A drive has an inertia of 10 kg-m ² , the developed torque of the motor is 100-0.1N Nm, the load torque is -20 Nm. N is the speed in rpm. What is the speed of the drive in steady state?	
Option A:	900 rpm	
Option B:	1200 rpm	
Option C:	-1200 rpm	
Option D:	800 rpm	
Q4.	When electric braking last for long periods, generally the maximum current is limited to	
Option A:	Double the rated value	
Option B:	The rated value	
Option C:	Thrice the rated value	
Option D:	Half the rated value	
Q5.	An operating point will be having steady state stability when	
Option A:	For a decrease in speed the load torue < Motor developed torque	
Option B:	For a decrease in speed the load torue > Motor developed torque	
Option C:	For a decrease in speed the load torue = Motor developed torque	
Option D:	For an increase in speed the load torue < Motor developed torque	

In case of flux control Speed is controlled above rated value Speed is controlled below rated value		
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Speed is controlled below rated value		
Torque remains unchanged		
Characteristic becomes linear		
Find the power rating of the motor for the load rising from 0 to 600 kW in 5 min		
120 kW		
268.33 kW		
346.41 kW		
600 kW		
CCM means		
Current continuous mode		
Continuous conduction mode		
Complete conduction mode		
Current conduction mode		
In dynamic braking of a DC separately excited motor, the time to stop is the		
braking resistor		
Independent of		
Increasing with		
Decreasing with		
Is twice the value of		
In static Scherbius drive, maximum value of firing angle is restricted to degree for		
the safe commutation of inverter thyristor		
90		
145		
165		
180		
In a vector control, while transforming parameters on synchronously rotating reference		
frame, the sequence of transformation is 's' represents stationary		
and 'e' synchronously rotating reference frame respectively.		
ds-qs to abc to de-qe		
abc to ds-qs to de-qe abc to de-qe to ds-qs		
· · · · ·		
de-qe to abc to ds-qs		
No-load speed of which of the following motor will be highest?		
Shunt motor		
Differentially compound motor		
Cumulative compound motor		
·		
Series motor		

Q13.	Select the wrong option with reference to the Torque Slip Characteristics of Three Phase I.M	
Option A:	s >1, Braking Mode	
Option B:	s < 0, Generating mode	
Option C:	$0 \le s \le 1$, Motoring mode	
Option D:	s is negative, Reverse Braking mode	
Q14.	Stator voltage control for speed control of induction motors is suitable for	
Option A:	Fan and pump drives	
Option B:	Drive of a crane	
Option C:	Drive of a low speed hoist	
Option D:	Constant torque drive.	
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Q15.	For regenerative braking, the motor which is not suitable is	
Option A:	DC shunt motor	
Option B:	DC compound motor	
Option C:	DC series motor	
Option D:	DC separately excited motor	
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Q16.	The speed of an induction motor with a constant torque load is controlled by stator	
	voltage control. For lower speed, the input current is	
Option A:	Lower than the rated value	
Option B:	Higher than the rated value	
Option C:	Equal to the rated value	
Option D:	Cannot determine	
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Q17.	In regenerative braking of a three phase induction motor, the phase angle of the stator voltage is	
Option A:	Less than 90 and greater than 45 degrees	
Option B:	Equal to 90 degree	
Option C:	Greater than 90 degree	
Option D:	Less than 45 degree	
Q18.	Compared to DOL starter, with STAR-DELTA starter the induction motor has starting torque	
Option A:	High	
Option B:	Equal	
Option C:	Low	
Option D:	Cannot compare	
Q19.	In V/f control, reduction in the supply frequency without a change in the terminal	
	voltage, causes	
Option A:	Increase in the air gap flux	
Option B:	Decrease in the air-gap flux	
Option C:	No change in the air-gap flux	
Option D:	First increase and then decrease in the air-gap flux	

Q20.	The quadrature axis component of stator current contributes power where the		
-	direct axis component contributespower across the air gap		
Option A:	Real, Real		
Option B:	Real, Reactive		
Option C:	Reactive, Real		
Option D:	Reactive, Reactive		
Q21.	Coulomb friction, viscous friction and static friction are high for a particular application. However, is/are not considered during the dynamic analysis.		
Option A:	Coulomb friction		
Option B:	Static friction		
Option C:	Viscous friction		
Option D:	Static friction and viscous friction		
Q22.	For the closed loop speed control of a DC motor with an inner current control loop, the inner loop should be that of the outer loop.		
Option A:	Faster than		
Option B:	Lightly slower than		
Option C:	Of same speed as		
Option D:	Much slower than		
Q23.	The carrier waveform of a sine PWM inverter is of 15 kHz frequency. When the fundamental output frequency of the inverter is 50 Hz, the inverter switches need to be turned-on and turned-off at a rate of		
Option A:	1000 times per second		
Option B:	10000 times per second		
Option C:	50000 times per second		
Option D:	15000 times per second		
Q24.	30 minutes rating of a motor is 50 kW. Determine the continuous rating of the motor if heating time constant is 90 min. Assume loss to be proportional to square of the power.		
Option A:	50 kW		
Option B:	26.62 kW		
Option C:	93.95 kW		
Option D:	85.45 kW		
Q25.	During light load of an intermittent duty cycle, an induction motor experiences		
Option A:	Acceleration		
Option B:	Deceleration		
Option C:	Reversal of the speed		
Option D:	Zero speed		

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Question	Correct Option (Enter either 'A' or 'B' or 'C' or 'D')
Q1.	В
Q2.	С
Q3.	В
Q4	В
Q5	А
Q6	А
Q7	С
Q8.	В
Q9.	В
Q10.	С
Q11.	В
Q12.	D
Q13.	D
Q14.	А
Q15.	С
Q16.	В

Q17.	С
Q18.	С
Q19.	А
Q20.	В
Q21.	В
Q22.	А
Q23.	D
Q24.	В
Q25.	А