Program: BE Mechanical Engineering Curriculum Scheme: Rev2016 Examination: Third Year Semester VI

Course Code: MEDLO6023 and Course Name: Industrial Automation

Time: 1 hour Max. Marks: 50

Note to the students:- All the Questions are compulsory and carry equal marks .

Q1.	The number of moveable joints in the base, the arm, and the end effectors of		
	the robot determines		
Option A:	Flexibility		
Option B:	Payload capacity		
Option C:	Operational limits		
Option D:	Degrees of freedom		
Q2.	Which of the following terms IS NOT one of the five basic parts of a robot?		
Option A:	Peripheral tools		
Option B:	End effectors		
Option C:	Drive		
Option D:	Controller		
Q3.	From the following which type of work envelope is made in jointed arm robot?		
Option A:	Rectangular work envelope		
Option B:	Cylindrical work envelope		
Option C:	Spherical or hemispherical work envelope		
Option D:	Linear envelop		
Q4.	Which is the following is continuous path controlled robot application.		
Option A:	Spot welding		
Option B:	Spray painting		
Option C:	Drilling holes		
Option D:	Machine loading and unloading		
Q5.	In car which type of timer is used for fan		
Option A:	on-delay		
Option B:	off-delay		
Option C:	on delay and off delay timer		
Option D:	no delay timer		
Q6.	Normally in latching circuit, the start switch is		
Option A:	Normally open and detent switch		
Option B:	Normally closed and detent switch		
Option C:	Normally open and spring return switch		
Option D:	Normally closed and spring return switch		

07			
Q7.	J L		
	Following symbol represents in PLC		
Option A:	Normally open contact		
Option B:	Carry '0' signal always		
Option C:	Normally closed contact		
Option D:	Capacitor		
option D.	Capacitor		
Q8.	Relay is used		
Option A:	Break the fault current		
Option B:	Sense the fault		
Option C:	Sense the fault and direct to trip the circuit breaker		
Option D:	Store the current		
-			
Q9.	Which one of the following is classified as input device in PLC systems?		
Option A:	Motor		
Option B:	Pump		
Option C:	Solenoid Valve		
Option D:	Sensor		
010			
Q10.	Which of the following motor has feedback control		
Option A:	DC motor		
Option B:	AC motor		
Option C:	Servo motor		
Option D:	Stepper motor		
Q11.	The speed of a BLDC motor can be controlled by		
Option A:	Changing input DC voltage		
Option B:	Changing temperature		
Option C:	Changing wind direction		
Option D:	Cannot be controlled		
Q12.	Solenoid valves are used in which applications		
Option A:	Hydraulics		
Option B:	Pneumatics		
Option C:	Electrohydraulic		
Option D:	Electro-hydraulic and electro-pneumatic		
012	"Stan the process involve corrective action" In this case the deviction of		
Q13.	"Stop the process invoke corrective action" In this case, the deviation or		
	malfunction requires that the execution of the work cycle beduring corrective action.		
Option A:	Continued		
Option B:			
Option C:	Suspended		
Option C. Option D:	Repeated		
Ծ բամու D .	Postponed		
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University of Mumbai

Examination 2020 under cluster 4 (PCE)

	Examination 2020 under diaster 1 (1 02)		
Q14.	A Group of CNC machines is which level of automation		
Option A:	Device level		
Option B:	System level		
Option C:	Machine level		
Option D:	D: Enterprise level		
Q15.	A safety monitoring system that sounds an alarm whengets dangerously		
	close to the automated system.		
Option A:	Human worker		
Option B:	Work piece		
Option C:	Control System		
Option D:	Actuator		
016			
Q16.	Which type of automaton line uses indexing around circular table		
Option A:	In line		
Option B:	Rotary		
Option C:	Single part		
Option D:	U shape linear		
017			
Q17.	Developing a spares inventory for current systems can also help reducein		
O 1: A	the event of a hardware failure.		
Option A:	Skill Time		
Option B:	Average Time		
Option C:	Down Time		
Option D:	Process Time		
Q18.	Which of the following statements are true for accumulators used in hydraulic		
Q16.	Which of the following statements are true for accumulators used in hydraulic systems?		
	1. Accumulator stores fluid with pressure		
	2. Accumulator stores fluid with pressure		
	3. Accumulator stores compressible liquid		
	4. spring is used as an external source to keep the fluid under hydraulic pressure		
Option A:	1, 3 and 4		
Option B:	2 and 3		
Option C:	1 and 4		
Option D:	2, 3 and 4		
- F · · ·			
Q19.	In pneumatic systems, AND gate is also known as		
Option A:	Check valve		
Option B:	Shuttle valve		
Option C:	Dual pressure valve		
Option D:	Flow control valve		
-			
Q20.	In pneumatic systems time lags are obtained by		
Option A:	Pneumatic-electric elements		
Option B:	Making the air to fill a volume after passing through a restriction		
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Option C:	Elongating the path of air	
Option D:	Using relay	
Орион Б.	Osing relay	
Q21.	How is proximity switch differentiated from limit switch?	
Option A:	Proximity switch is activated when moving parts have physical contact with it	
Option B:	Proximity switch is activated when non-moving parts have physical contact	
Option C:	Proximity switch is activated when moving parts are close to it	
Option D:	Proximity switch is activated when magnetic parts have physical contact	
Q22.	A double acting cylinder can be controlled by a final control valve	
Option A:	3/2 DCV	
Option B:	5/2 DCV	
Option C:	Dual pressure valve	
Option D:	2/2 DCV	
Q23.	One notable difference between the hydraulic as compared to pneumatic is that	
	the return fluid is	
Option A:	Vented to atmosphere	
Option B:	Sent back to reservoir	
Option C:	Sent back to cylinder	
Option D:	Stored in line	
Q24.	In pneumatic systems the medium used is	
Option A:	Air	
Option B:	Low viscous oil	
Option C:	hydrogen	
Option D:	high viscous oil	
Q25.	Which of the following is applicable for bleed off circuits?	
Option A:	develop heat in the system	
Option B:	used for resistive loads	
Option C:	used for heavy loads	
Option D:	used for light loads	
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Question	Correct Option (Enter either 'A' or 'B' or 'C' or 'D')
Q1.	D
Q2.	A
Q3.	С
Q4	В
Q5	В
Q6	С
Q7	A
Q8.	С
Q9.	D
Q10.	С
Q11.	A
Q12.	D
Q13.	В
Q14.	В
Q15.	A
Q16.	В
Q17.	С
Q18.	С
Q19.	С
Q20.	В
Q21.	С
Q22.	В
Q23.	В
Q24.	A
Q25.	В