# University of Mumbai <br> Examination 2020 under cluster 4 (PCE) 

Program: BE Electronics and Telecommunication Engineering Curriculum Scheme: Rev2016<br>Examination: Third Year Semester VI<br>Course Code: ECCDLO 6022 and Course Name: Radar Engineering<br>Max. Marks: 50

Time: 1 hour

Note to the students:- All the Questions are compulsory and carry equal marks .

| Q1. | What is the frequency range for L Radar frequency band |
| :--- | :--- |
| Option A: | $1-2 \mathrm{GHz}$ |
| Option B: | $2-4 \mathrm{GHz}$ |
| Option C: | $4-8 \mathrm{GHz}$ |
| Option D: | $8-12 \mathrm{GHz}$ |
|  |  |
| Q2. | A radar signal takes $200 \mu$ s to travel towards the target and back find the range of <br> the target. |
| Option A: | 40 km |
| Option B: | 50 km |
| Option C: | 35 km |
| Option D: | 30 km |
|  |  |
| Q3. | Noise bandwidth is measured in the receiver in block |
| Option A: | mixer |
| Option B: | Video amplifier |
| Option C: | IF amplifier |
| Option D: | Second detector |
|  |  |
| Q4. | A radar measures an appearent range of 8nmi when prf is 4000 Hz but it measure <br> an appearent range of about 19 nmi when prf is 3500 Hz what is the true range? |
| Option A: | 97 nmi |
| Option B: | 78 nmi |
| Option C: | 99 nmi |
| Option D: | 88 nmi |
|  |  |
| Q5. | The maximum range R of detection of target is proportional to ? of the <br> transmitted power. |
| Option A: | square root |
| Option B: | square |
| Option C: | fourth root |
| Option D: | one-fourth |
| Q6. |  |
| Option A: | What is Vr related to Doppler frequency shift |
| Option B: | Relative voltage |
| Option C: | Repeller voltage |
| Option D: | Repeller velocity |
| Q7. | Staggered pulse concepts is used to remove |
|  |  |

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| Option A: | In equality |
| :--- | :--- |
| Option B: | Blind speed |
| Option C: | Matching |
| Option D: | Blind range |
|  |  |
| Q8. | The minimum range of detection by a pulse radar depends on |
| Option A: | pulse width |
| Option B: | average transmitter power |
| Option C: | beam width of the antenna |
| Option D: | bandwidth |
|  |  |
| Q9. | The coho in MTI radar operates at the |
| Option A: | intermediate frequency |
| Option B: | transmitted frequency |
| Option C: | received frequency |
| Option D: | pulse repetition frequency |
|  |  |
| Q10. | Blind speed causes target to appear |
| Option A: | moving uniformily |
| Option B: | moving irregularly |
| Option C: | stationary |
| Option D: | intermittentaly |
|  |  |
| Q11. | STALO' stands for |
| Option A: | standard local oscillator |
| Option B: | stable L-band output |
| Option C: | stabilized local oscillator |
| Option D: | staturated and linear oscillator |
|  |  |
| Q12. | When P is the peak transmitted pulse power, the maximum range of the radar is <br> proportional to |
| Option A: | P |
| Option B: | (P)1/2 |
| Option C: | (p)1 /4 |
| Option D: | (1))114 |
| Q13. |  |
| Option A: | MTI radar operates at 10 GHz with PRF of 3000 ppps. The lowest blind will be |
| Option B: | $66 \mathrm{km/hr}$ |
| Option C: | $81 \mathrm{km/hr}$ |
| Option D: | $162 \mathrm{km/hr}$ |
| Option B: | Lobe switching or serquential switching |
| Option D: | Conicalse Scan |
| Low angle tracking |  |
|  |  |
|  | The tracking technique that derives angle error information on the basis of a |

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|  |  |
| :--- | :--- |
| Q15. | Lobe switching gives |
| Option A: | angular error |
| Option B: | Range |
| Option C: | Velocity |
| Option D: | Target Size |
|  |  |
| Q16. | In conical scan, radar the beam is |
| Option A: | Rotated continuosly |
| Option B: | Rotated in 2 steps |
| Option C: | Rotated in 4 steps |
| Option D: | Rotated in 360degree |
|  |  |
| Q17. | Monopulse is a method |
| Option A: | Simultaneous lobing |
| Option B: | sequential lobing |
| Option C: | Conical Scanning |
| Option D: | Random lobing |
|  |  |
| Q18. | The main advantage of TWT over a multi-cavity klystron is |
| Option A: | greater bandwidth |
| Option B: | more efficient |
| Option C: | higher number of modes |
| Option D: | higher output power |
|  |  |
| Q19. | Which one of the following can be used for the amplification of microwave <br> energy <br> Option A: <br> traveling-wave tube <br> Option B: |
| Option C: | Reflex Klystron |
| Option D: | Gunn diode |
|  |  |
| Q20. | Which of the following is solid state device |
| Option A: | Magnetron |
| Option B: | Travelling wave Tube |
| Option C: | Klystron |
| Option D: | GaAs MOSFET |
|  |  |
| Q21. | One of the following is a crossed field device |
| Option A: | Magnetron |
| Option B: | Travelling wave Tube |
| Option C: | Two cavity klystron |
| Option D: | Reflex klystron |
|  |  |
| Q22. | Phase difference between adjacent resonators in an N-resonator travelling <br> magnetron is given by, where n is an integer |
| (2л/N) radians |  |
|  | (2rn/N) radians |

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| Option C: | $2 \pi n$ radians |
| :--- | :--- |
| Option D: | $\mathrm{n} / \mathrm{N}$ radians |
|  | The intensity modulated map like circular display that gives target location in <br> polar coordinates |
| Q23. | F-scope |
| Option A: | A-scope |
| Option B: | A-scope |
| Option C: | B-scope |
| Option D: | PPI |
|  |  |
| Q24. | Noise figure for a receiver is defined as the ratio of |
| Option A: | (S/N) ratio at the input to (S/N)ratio at the output |
| Option B: | (S/N) ratio at the output to (S/N)ratio at the Input |
| Option C: | S/N ratio at the input |
| Option D: | $\mathrm{S} / \mathrm{N}$ ratio at the output |
|  |  |
| Q25. | Noise Factor(F) and Noise Figure(NF) are related as |
| Option A: | $\mathrm{F}=10$ log10(NF) |
| Option B: | $\mathrm{NF}=10$ log10(F) |
| Option C: | . NF $=10(\mathrm{~F})$ |
| Option D: | $\mathrm{F}=10(\mathrm{NF})$ |

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| Question | Correct Option <br> (Enter either ' $A$ ' or ' $B$ ' or ' $C$ ' or ' $D$ ') |
| :---: | :---: |
| Q1. | B |
| Q2. | D |
| Q3. | C |
| Q4 | D |
| Q5 | C |
| Q6 | B |
| Q7 | B |
| Q8. | A |
| Q9. | A |
| Q10. | C |
| Q11. | C |
| Q12. | C |
| Q13. | D |
| Q14. | B |
| Q15. | A |
| Q16. | A |
| Q17. | A |
| Q18. | A |
| Q19. | A |
| Q20. | D |
| Q21. | A |
| Q22. | B |
| Q23. | D |
| Q24. | A |
| Q25. | B |

